

NUMERICAL METHODS-LECTURE XIII:  
A PRACTICAL DISCUSSION OF GMM/MSM  
(or; How to Estimate a Structural Model)

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# INTRODUCTION

- ▶ We will play fast and loose with the term “GMM”
- ▶ Much of the time I just mean a “minimum distance” estimator
- ▶ That said, GMM is the best
- ▶ A way to “calibrate” or estimate your model
- ▶ Take your model seriously and have it interact with the data
- ▶ Don't have to target entire distribution: require your model to say something without saying everything

# GMM

- ▶ First, forget everything you know.
- ▶ In most uses, GMM is making your fit look like the data, just like least squares
- ▶ Only difference is the moment conditions
- ▶ Let's do an extremely transparent example (!?)

## EXAMPLE: SETUP

- ▶ Agents like Medicaid, private health insurance, and consumption

$$U_i(m_i, p_i, c_i) = \log(c_i) + \psi_{1,i}m_i + \psi_{2,i}p_i$$

Where they have the budget constraint:

$$Inc_i = c_i + P_p p_i + P_m m_i$$

And where:

$$\begin{bmatrix} \psi_{1,i} \\ \psi_{2,i} \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma_{\psi_1}^2 & \sigma_{\psi_1\psi_2}^2 \\ \sigma_{\psi_1\psi_2}^2 & \sigma_{\psi_2}^2 \end{bmatrix} \right)$$

$$Inc_i \sim \log \mathcal{N}(\mu_{Inc}, \sigma_{Inc}^2)$$

## EXAMPLE: ESTIMATION ASSUMPTIONS

- ▶ Given  $P_p, P_m, \mu_{\psi_1}, \mu_{\psi_2}, \sigma_{\psi_1}^2, \sigma_{\psi_2}^2, \sigma_{\psi_1\psi_2}^2, \mu_{Inc}, \sigma_{Inc}^2$

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## EXAMPLE: ESTIMATION PROCEDURE

1. Extract moments from “true dataset.”
2. Assume a set of parameters.
3. Simulate dataset.
4. Compare simulated parameters to true parameters.
5. Take weighted sum of squared differences.
6. With a new set of parameters, start back at 3
7. Continue until your simulated parameters are as close as can be

## EXAMPLE: IDENTIFICATION

- ▶ It's worth thinking about how we identify preferences
- ▶ We'll identify based off behavior: what people actually do
- ▶ Moreover, we assume they maximize, so take FOC's/maximize
- ▶ In this case, maximize.
- ▶ Want to estimate  $\psi_1, \psi_2, \psi_3, \sigma$

## EXAMPLE: ESTIMATION MOMENTS

- ▶ How do you choose moments?
  
- ▶ I choose (haphazardly):
  1. Proportion of households that have no insurance
  2. Proportion of households with only one medicaid contract
  3. Proportion of households with 1 medicaid contract that have at least one private insurance contract
  4. Average level of consumption (3)
  5. Standard deviation of consumption ( )
  6. Conditional on having any insurance, mean consumption
  7. Conditional on having any insurance, standard deviation of consumption
  8. Proportion of households that have more than 5 contracts
  9. Correlation of  $m$  and  $p$
  10. Correlation of  $m$  and  $c$
  11. Correlation of  $c$  and  $p$



## EXAMPLE: ESTIMATION MOMENTS

- ▶ The core of GMM here is, after creating the simulated population:

$$f(\Theta) = \begin{bmatrix} [\text{length}(\text{find}(\text{best}_m == 0 \& \text{best}_p == 0)) ./ \text{num}] \\ [\text{length}(\text{find}(\text{best}_m == 1)) ./ \text{num}] \\ \vdots \\ [\text{mean}(\text{best}_c(\text{find}(\text{best}_m + \text{best}_p > 0)))] \end{bmatrix}$$

- ▶ And, with `moment(:,1)` holding the simulated moments and `moment(:,2)` holding the targets,

$$\text{error} = \text{sum}((\text{moment}(:,1) - \text{moment}(:,2)).^2)$$

## EXAMPLE: ESTIMATION MOMENTS

See Main.m and Estimation.m (and Data.m for the “true” data generating process!)

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## OKAY...I THINK I GET IT(?)

- ▶ Do you?
- ▶ Also see a general equilibrium version of firm taxation in separate files Main.m and Estimator.m
- ▶ I still don't get the notation and the optimal part...

## A LITTLE ON NOTATION

- ▶ You normally see GMM written like:

$$\beta_N = \arg \min_{\beta \in \mathbb{P}} g_N(\beta)' W g_N(\beta)$$

- ▶ Where  $g_N(\beta) = \frac{1}{N} \sum_{i=1}^N f(x_t, \beta)$ , where your moment condition is:  $E_t(f(x_t, \beta)) = 0$

- ▶ Let  $ME_1$  stand for “Moment error 1”, then  $g_N(\beta)' W g_N(\beta)$  is really just:

$$\begin{bmatrix} ME_1 \\ ME_2 \\ ME_3 \\ \vdots \\ ME_r \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \begin{bmatrix} ME_1 & ME_2 & ME_3 & \cdots & ME_r \end{bmatrix}$$

- ▶ Note that because of how I wrote the weighting matrix, this is just the sum of squared errors:

$$ME_1^2 + ME_2^2 + ME_3^2 + \dots + ME_r^2$$

## A LITTLE ON THE BEST CHOICE OF $W$

- ▶ You'll note that some of my moment choices are pretty correlated
- ▶ With this weighting, you give one data concept multiple weights
- ▶ But let's now take the variance-covariance matrix of our moments:

$$V = \left( \begin{array}{c} \left[ \begin{array}{c} ME_1 \\ ME_2 \\ ME_3 \\ \dots \\ ME_r \end{array} \right] \\ \left[ ME_1 \quad ME_2 \quad ME_3 \quad \dots \quad ME_r \right] \end{array} \right)$$

(Or, with many data points the sample mean of the same thing)

- ▶ Then use  $V$  as your new  $W$
- ▶ What is this doing?

## A LITTLE ON THE BEST CHOICE OF $W$

- ▶ This is just weighted least squares
- ▶ But more numerically, what  $V$  is getting at is the information in a given moment condition
- ▶ Every moment is saying something about your  $\theta$ 's
- ▶ What the weighting matrix does is listens more to:
  - ▶ Moments that are more consistent (not a lot of noise)
  - ▶ Moments that move a lot for small deviations of  $\theta$
- ▶ That second is particularly interesting, and should a bit like the information matrix?
- ▶ When your model blows up with small changes in the parameter, it means the parameter is very precisely pinned down
- ▶ Good and bad, bad and good.
- ▶ From a practical standpoint,  $W = I$  with slight tweaks for moments of different absolute magnitude gets you pretty far



## CALIBRATION VS. ESTIMATION

- ▶ Fundamentally, model uncertainty about parameters comes from sensitivity
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- ▶ This may help the information matrix's relation to standard errors make sense to you!

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- ▶ It also makes clear that robustness checks are doing the same thing!
- ▶ It's the *Change* in your score.
- ▶ For whatever reason, it's relatively rare to report standard errors when you don't touch microdata
- ▶ More typically, you see "calibration" and "robustness" rather than "estimation" and "standard errors."
- ▶ "Estimation is when you care about your standard errors."

## SECOND, FIRM-SIZE MODEL

- ▶ Many firms, with production function:

$$Y_i = A_i L_i^\alpha$$

- ▶ And profit function:

$$\pi_i = Y_i - wL_i$$

- ▶ Many households with labor supply FOC:

$$L = \frac{2w}{\psi + 0.002w^2}$$

- ▶ Supply and demand must hold:

$$\sum_{h \in \{HH\}} L_h = \sum_{f \in \{F\}} L_f$$